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Existence and Unicity of Solutions 151 4.11

Summary 153 4.12 Notes and References

153 4.13 Exercises 154 5. Describing

Function Analysis 157 ... 5.7 Exercises 188

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Part II: Nonlinear Control Systems Design

191 Introduction to Part II 191 6. Feedback

Linearization 207

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$\ddot{\theta} = -\frac{g}{l} \sin \theta - k \dot{\theta}$, where $l > 0$ is the length of the pendulum, $m > 0$ is the mass, $k > 0$ is a friction parameter and θ is the angle subtended by the rod and the vertical axis through the pivot point, see Figure 1.1. PSfrag replacements Figure 1.1 The pendulum in Exercise 1.1

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Exercise 1.2 The behavior of a dynamical system is described by the equation $\ddot{x} + 1.5\dot{x} + 0.5x + f(x) = 0$, $f(x) = x^2 + [x(1)]^2$
(1) Determine the region of x , such that $X = 0$ is an exponentially stable equilibrium

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point of the given system. Solution. Denote $x_1 = x$; $x_2 = \dot{x}(1)$, and $X = [x_1; x_2]^T$. Hence, we have

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